Physics 361 - Machine Learning in Physics

Lecture 5 – Basics of Machine Learning

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Unit 2: Machine Learning Basics

2.1 Machine Learning concepts using the example of Linear Regression (cont.)

Linear regression (cont'd) Very simple ML model: Simple IVIL monice.

X: injet

y: oatpat (aa be minimized w.r.t. to w: W = (X train T X train) X train T Y train

Last slide: y was a 1-dimensional output.
We can also have multidimensional regression fargets:

 $victor output = M \times + h$ $(bifori we had y = \vec{w}^T \vec{x})$

- These Linear transformations are called Linear Layers in maching Learning.
- Side note: While linear models are analytically solvable (for invertible M), for very high dimensional problems it is more efficient to solve them by optimization.

Polynomial regression

ola polynomial regression we fit a higher order polynomial,

E.g. 2nd order pol. $\hat{y} = b + w_1 \times + w_2 \times^2$

General: $y = b + \sum_{i=1}^{n} w_i \times i$

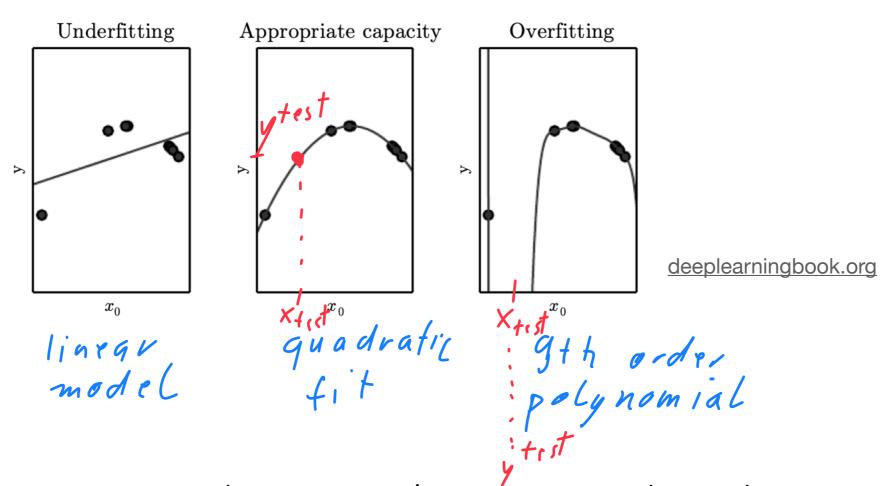
. This model can be solved for w with the same equations as Linear regression heraust it is still Liniar on the parameters

Capacity, Overfitting, Underfitting

- * How will does a model trained/fitted to the training data work on noveldata, =) Gregeralization error
- We usually assame that fraining data and test data are drawn from the same distribution. "i.i.d." data: independent ideantically distributed
 - Grancalization is closely related to over fitting and underfitting,

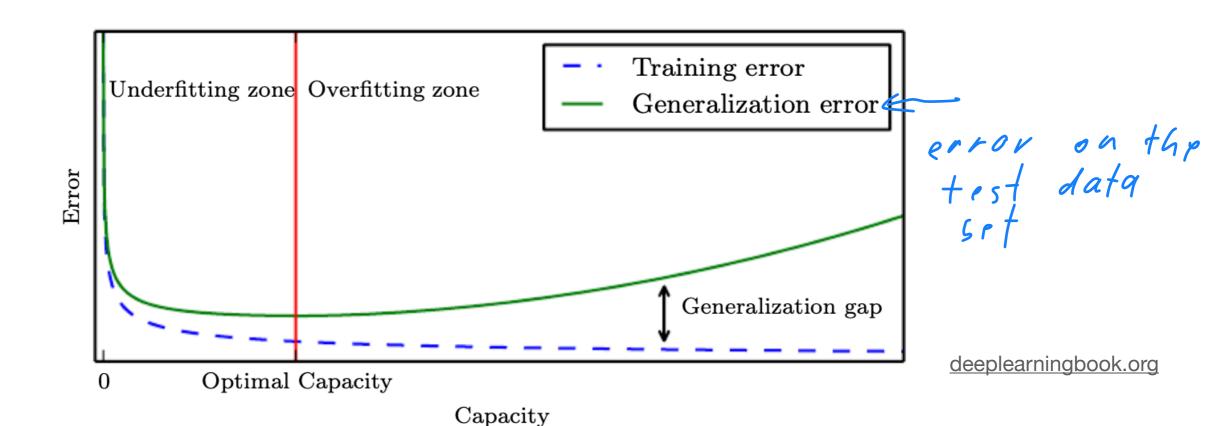
underfit: training error is Large overfit: training error is small but test error is Large.

Example of polynomial trgression:



- The space of fauctions that the model can represent is called the capacity.
- · Occam's pazor: chose the simplest, that fits"
- · Lower capacity -> tends to generalize better Higher capacity -> reduces training error,
- => Need to optimize the capacity or tegularize.

Typical behavior of error us capacity (after training out the model)



we could e.g train models with various numbers of neural network layers.

Usually this is not the main approach.

Instead we use "regularization" to avoid over fitting.

Regularization

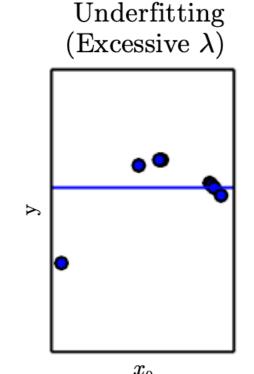
oldea: Keep the model capacity fix, but encourage simpler solutions.

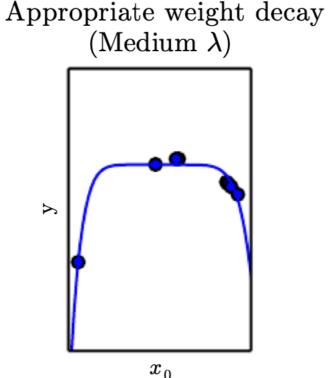
· Common method: weight decay

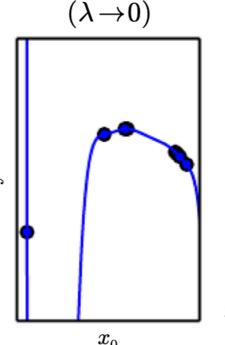
New Loss fo minimize $J(\vec{w}) = MSE_{train} + \lambda$

parameter to chose "Lambda" W W W L-2 norm L-2 regularization

This discourages Large weights







Overfitting

deeplearningbook.org

L-2 regularization is one of sereral popular methods of regularization

Regularization: any method meant to prevent over fitting without changing the model capacity.

Two ofher popular methods which we discuss later:

- drop-out
- early stopping.

Hyperparameters

- · Hyperparameters are parameters that are NOT part of the fifting/optimization procedure,
- · Examples: « model architecture es -maximum
 - eg-maximum order of polynomials
 - depth of a negral network
 - · Learning parameters
 - e.g. Learning rate
 - · Regularization parameters e.g. 2
- To chose the best hyperparameters one often splits off a validation data set from the training data (n 20% there of).

Relation of MSE and maximum Likelihood

- In Linear respession we were Learning y from x.

 Instead now we want to Learn P(y1x).

 => we get an error bar.
- If we assume that the error is Ganssian

 we want to Learn: $P(y|x) = N(y|\hat{y}(\hat{x},\hat{w}))$
- The Loss is now the Likelihood mean of width of the training data: $\begin{cases}
 (\theta) = \sum_{i=1}^{\infty} \log p(y_i|x_i^{(i)};\theta) \\
 \sum_{i=1}^{\infty} \log p(y_i^{(i)}|x_i^{(i)};\theta)
 \end{cases}$ and of parameters, here $\theta = w_i$ in Linear = m_i Log($z\pi$) $\sum_{i=1}^{\infty} \frac{|\hat{g}_{(i)}^{(i)} y_i^{(i)}|^2}{|g_{(i)}^{(i)} y_i^{(i)}|^2}$

· We want to maximize flis with respect to 6. Maximize L'is the same as minimizing MSE.

Course logistics

- Reading for this lecture:
 - For example: Deeplearningbook.org 5.
- Problem set: First problem set end of this week.